Holonic Manufacturing system and Its Application

¹Zhao Jiang, ²Yuhong Tai, ³Gaofu Xu

¹ University of Shanghai for Science and Technology, Shanghai, China

² University of Shanghai for Science and Technology, Shanghai, China

³ University of Shanghai for Science and Technology, Shanghai, China

Email: jzgood@163.com

Abstract –Facing the increasingly diversified customer need and the fierce market competition, manufacturing production mode towards the customization, The AM (Agile Manufacturing) mode is expected to become the trend of the development of the 21st century. This paper studies the main characteristics of agile manufacturing and points out that the holonic manufacturing system to be the important base of realizing AM. And then analyze the function and basic characteristics of the holonic system. Finally, put the concept and the theory into applying in manufacturing system design.

Keywords -- Holon; Holonic structure; manufacturing system; Agile Manufacturing

1. Introduction

The fierce market competition on manufacturing put forward severe challenges, make flexible and dynamic changes in the global market of the fast response ability to become the manufacturing competition focus. Holonic Manufacturing System is considered as the basis of agile manufacturing to get serious in-depth study from international cooperation research institutions. This paper on the basis of the concept of Holon, study it in the field of theory application. Holon is a complex system and has the "whole" and "Part" attribute, which has "autonomy" and with "coordination" entity since it is not only contain the whole (Self - contained - whole) and interdependent parts (Dependent - Part). Arthur Koestler Based on the following two starting point puts forward the concept of Holon: (1) some relative stable intermediate form is favorable for the development of complex system, any complex system have some form of hierarchical structure; (2) the whole and part of the concept of relativity.

2. Holonic manufacturing system and the traditional manufacturing system

HMS (Holon Manufacturing system) has three features (1) the processing disturbance stability and reliability; (2) the processing system change the adaptability and flexibility; (3) the effective use of to the service. The difference between Holonic structure manufacturing control system and the traditional manufacturing control system can see table 1.

Traditional Manufacture Control System	HMS manufacture Control System
1.Business objectives in the form of task decomposition is	1.Business objectives in the form of target
decomposed step by step	decomposition is decomposed step by step
2. Coordinate and integrate lower activity by the upper	2. Through the coordination between the Holon to complete the
	tasks assigned by the upper
3.Master-slave relation	3.Peer relationship
4. Rigid static structure	4. Flexible and variable dynamic structure
5.Certain communication mode and fixed message transfer	5. Variable communication mode and flexible message transfer
structure	mechanism
6.Poor reliability, system strain capacity is decided by system design	6.System reliability is high, the system has the ability of dynamic reconfiguration
7.Intelligent decision focused on the control structure of the upper	7.All levels of all-around body have some degree of intelligence
8. Suitable for relatively stable manufacturing environment	8. Suitable for dynamic changeful manufacturing environment

Tab.1 Contrast of Traditional and HMS manufacture Control System

3. Remote service integrated management system structure based on Holon

By introducing the performance of consultation with autonomy Holon concept, construct the face crossdomain enterprise based on the Holon remote service integrated management system structure, as shown in figure 1.



Figure 1 Remote Service Integrated Management System Structure Based on Holon

4. Remote service dynamic allocation and optimization scheduling

Through the service Holon and consultation coordination of Holon an important characteristic is in the application of evolutionary algorithm search to individual process have multiple Holon participation, will Holon internal coordination strategy, target function and evaluation standards and coordination Holon algorithm combining process. Each service Holon packaging the domain knowledge, target, beliefs and strategies, in the design of automatic consultation service Holon strategy mechanism, each Holon strategy module Settings a elastic interval, is the goal function set a variable parameter, in the realization of different goal of the whole supply chain using the corresponding parameter value. The project depends on the coordination of the Holon service target, beliefs and strategies, these strategies and faith by coordination Holon of supervision and guidance, coordination Holon according to service Holon team set goals for project evaluation, make each suit Holon using method of cooperation coordination strategy. Service Holon activity plan receiving standard application of simulated annealing algorithm, can avoid the local search and mess up, service Holon scheme accept standard function :

$$P(A_{i}(C,C')) = yes = \begin{cases} 1, if f_{i}(c') \ge f_{i}(c) \\ e^{(f_{i}(c') - f_{i}(c))/T}, otherwise \end{cases}$$

Type, P represent alternatives receiving probability, At (C, C ') represent the C 'plan instead of C solution acceptance criteria, on behalf of the plan C, C' utility function, T representative (temperature) control parameters, scheme acceptance criteria using utility decreasing principle, if the new scheme C 'utility is greater than the plan C utility, the new scheme C' instead of plan C, otherwise, not to the new scheme all negative, but for the new plan to certain receiving probability, so it can increase the probability of find optimization scheme, and At the same time avoid search stalemate. In the hierarchical control, all decision-making ability is in system design decomposition to hierarchical control of all levels.

Figure 2, for enterprise remote service Holon dynamic allocation mechanism. Scheduling Holon through and order Holon cooperation, the periodic or based on event scheduling adjustment technology, constantly adjust scheduling plan in order to optimize the service distribution. Scheduling Holon first through the order processing module scheduling Holon through and order Holon cooperation, the periodic or based on event scheduling adjustment technology, constantly adjust scheduling plan in order to optimize the service distribution. Scheduling Holon uses the order processing module.



Figure 2. Remote Service of Enterprise-Dynamic Allocation Mechanism of Holon

5 Case

In a certain enterprise remote service platform as an example, based on the genetic algorithm ant clustering kind of remote service allocation methods are tested, analyzed its effect. Based on genetic algorithm (ant clustering algorithm design such as follows:

1) Chromosome selection, coding and generating of initial population: chromosome using ant colony algorithm of parameter: a, beta, p, t, q. This can be used to determine genetic algorithm with ant colony algorithm for the optimal parameter combination; Because the real coded genetic algorithm has high accuracy, large search space, easy into a certain heuristic information field etc, the ant clustering algorithm class USES the decimal number coding; The initial population according to the preset by random number generating way.

2) Fitness function, the selection of fitness function and to solve problems, combining the objective function decided in this paper, the fitness function F is defined as F = Fr., including Fr to assess clustering algorithm of F -Measure function. F - Measure, the higher the value, the corresponding individual fitness is higher.

3) The selection operator, the tournament selection method, according to fitness function selected cross individual. In the championship choice method, random selected from population reservation number of individuals, and then from these individuals choose to have the best fitness individuals do father individual, this process is repeated, until all the father individual selection.

4) Crossover operator, the uniform cross method, uniform cross more generalized change, each point as potential intersection, the destructive can promote to search the solution space, can search to other cross method can't search to the model. The process is first random generation and elder individual coding long binary cross template string, and then according to this template string to two father individual genes are string cross, get two new generations individual. 5) mutation operator, the gauss mutation methods, this method originated in the evolution strategy. In general evolution strategy of an individual contains two elements (x, or), one of the first vector x says the search space of a point, the second vector or said standard deviation. Future generations (x', or') by type generation:

$$\sigma' = \sigma e^{N(0, \Delta \sigma)}$$

X'=X+N(0, \Delta \sigma)

The N $(0, \Delta \sigma)$ is mean for 0, standard deviation for its independent Gaussian random number vector. According to the above description, ant clustering kind of algorithm process is as follows:

Step 1 Set the parameters, generate initial population

- Step 2 Calculate fitness function value for all individuals use ACA
 - Set parameters initialize pheromone trails
 - While termination iteration not met or clustering center changed) Do
 - Determinate clustering for each data x with probability p_{ij} (t) given by equation(1)
 - Update clustering centers for each clustering by equation (3)
 - Update pheromone on each walked edge by equation (4) and (5)
 - Calculate fitness function value
- Step 3 Genetic operation
 - Sort all individuals according to fitness function ;
 - Select individuals through Stochastic Uniform selection method ;
 - Carries on Scattered Crossover and the Mutation operation to the selected individuals ;
- Step 4 Repeat step 2 and step 3 until met the termination iteration

End ACGA

Take the metric value (F - Measure) as a method for clustering algorithm evaluation function. F-Measure fusion of the information retrieval precision rate and recall rate thoughts, F -Measure the higher the value, the clustering, the better the results. A clustering J and related to this classification I of the precision ratio and recall ratio is defined as:

$$P(i, j) = N_{ij} / N_j$$
$$r(i,j) = N_{ii} / N_i$$

Among them is in the clustering j in classification of I prime; J is the prime classification I, J is clustering j of prime, classified I F - Measure defined as:

$$F(i) = \frac{2PR}{(P+R)}$$

$$F_{measure} = \frac{\sum_{i} N_{i} F(i)}{\sum N_{i}}$$

Experimental data using UCI machine learning repository Wine, Iris data set and Cork Stoppers data set, see table 2.

Tab 2The Description of Test Data Set				
Data set	Attribute number	Classificati on number	The number of examples	
wine	13	3	178	
Iris	4	3	150	
Cork stoppers	10	3	150	

Test data set respectively with ACA (ant colony optimization) and ACGA (based on the genetic algorithm ant clustering class) testing. In ACA, parameter a, beta, p, t, q respectively take 40100, 0.1, 20300, maximum iterating times take 30 times. In the GACA population

size is 30, crossover probability is $0 \cdot 8$, mutation probability for $0 \cdot 2$, maximum algebra is 50.

Figure 3 shows the Iris data set in 150 data and clustering results, (a) and (b) respectively is ACA and ACGA examples of clustering Iris data gathering class results in the photo, train, \circ and mouth said Setosa category respectively, Versico - lour and Virginica.



(a) ACA Clustering results. (b) ACGA Clustering results.Figure 3 the data set of Iris and Clustering results

From the photos can intuitively see ACGA ACA is clustering effect is better, more close to the real classification. Table 2 shows the use of ACA and ACGA

respectively on two data sets for 50 times the average test results.

Tab3The two kinds of test results				
Data Set				
Algorithm	Wine	Iris	Cork Stoppers	
ACA	0.721	0.892	0.854	
ACGA	0.761	0.920	0.861	

According to table 3 comparisons, in the experiment the clustering number hypothesis is known and the data set classification number the same. From the test results can be seen in ACGA accuracy than ACA algorithm are improved to varying degrees, so as to realize the crossdomain between enterprise remote service reasonable configuration and optimization scheduling, achieve enterprise remote service configuration from consultation, the modern enterprise has a good environmental adaptability.

8. Conclusions

This paper will Holon theory is introduced into the remote service configuration management, the first constructs face cross-domain enterprise based on the Holon remote service integrated management system structure, then through the description enterprise remote service between Holon data and function relationship, constructing service between Holon consultation scheme receiving standard and service between Holon communication protocols, based on Holon enterprise remote service optimization scheduling mechanism; By constructing a Holon based on remote service control model of the communication mechanism, set up based on the Holon enterprise remote service optimization scheduling mechanism, and finally, and on this basis, Holon based on remote service automatic negotiation rules and strategy, so as to realize the cross-domain service between enterprise remote reasonable configuration and optimization scheduling, achieve enterprise remote service configuration from consultation, the modern enterprise has a good environmental adaptability, to solve the cross-domain between enterprise remote service configuration and scheduling problem in the process of consultation, make the enterprise has a good environmental adaptability, improve production efficiency.

References

- Zhou yanfbi, FaJl cheng, Ji penghua, Leng sheng, a Holonic Framework of Reconfigurable Shop Floor control System in Automated Manufacturing systems
 [J], 11ransactions of Nanjing university of Aeronautics & Astronautics, 1999. 1, 59-67:
- [2]. Jo Wyns, PhD dissertation, Reference architecture for Holonic Manufacturing Systems-the key to support evolution and reconguration [M], PMA / K. U. Leuven, 1999
- [3]. HIMoN, The sciences of the Artificial 6th [M],MIT Press Cambridge, 1990
- [4]. Gilad Langer, HoMuCS. a Methodology and Architecture for Holonic Multi-cell Control Systems [J], Technical University of Denmark, 1999
- [5]. McFarlane D. C, Holonic Manufacturing systems in continuous processing: concepts and control requirements [J], Intelligent Control of Integrated Mallufkturing Systems, Lisboa, Portugal, Alfamicro. 1995, 25-28.
- [6]. Suda H., Future Factory System formulated in Japan[J], Tbchno Japan, 1990, 3(3):2-4

- [7]. Brussel Ht Wyns J. Valckenaers P, Bongaerts L., Reference architecture for holonic manufhcturing systems: PROSA [J], Computers in Industry,1998, 37(2): 255-274
- [8]. Junwei Yan, Feiming He, Chuan Mu. The Architecture of Construct-Based Enterprise Modeling and its Modeling Approaches [C], Proceedings of 2000 International Conference on Advanced Manufacturing Systems and Manufacturing Automation, 2000, guangzhou: 679-682
- [9]. Marcos wilson C. Aguiar, Richard H. A modeldriven Approach to Enterprise Integration[J]. Computer Integrated Manufhcturing systems,1995, 8(3): 222-224
- [10]Nabeel Arshad, Muhammad Ali Jamal, Dur E Tabish, Saqib Saleem, Effect of Wireless Channel Parameters on Performance of Turbo Codes, Advances in Electrical Engineering Systems, Vol.1, No. 3, 2012, pp. 129-134.
- [11] Fahad Shamshad, Usman Javed, Saqib Saleem, Qamar-ul-Islam, Physical Layer Aspects of 3GPP's Long Term Evolution (LTE), Advances in Computer Science and its Applications, Vol. 2, No. 1, 2012, pp. 287-294.
- [12] Fahad Shamshad, Muhammad Amin, Simulation Comparison between HFSS, CST and WIPL-D for Design of Dipole, Horn and Parabolic Reflector Antenna". Advances in Computer Mathematics and its Application, Vol. 1, No. 4, 2012, pp.203-207.

Vitae

Zhao Jiang, Was born in 1986. He obtained a Bachelor degree in Engineering management in Civil engineering college from Jiangsu University of Technology and Science.

He now is a student in University of Shanghai for Science and Technology, Shanghai, China. His research is industrial engineering.

Gaofu XU is also the graduate students in the School of Management from University of Shanghai for Science and Technology.

Yuhong Tai is an associate professor from Shanghai university of science and technology, her research direction is project management